## Homework 5

## May 25, 2017

Problem 1. Braess book, Chapter 1, 4.8, 4.9

4.8

*Proof.* Consider the function W(x) on  $\Omega_h$ .

$$W(x) := \begin{cases} h^2, \ x \in \Omega_h \\ 0, \ x \text{ on } \partial \Omega_h \end{cases}$$
(1)

It can be verified that

$$L_h W(x) := \begin{cases} \ge 1, \ x \in \Omega_h \backslash \Omega_{h,0} \\ 0, \ x \ on \ \Omega_{h,0} \end{cases}$$
(2)

Hence,  $L_h(V-W) \leq 0$  in  $\Omega_h$ , and  $V \leq W$  on  $\partial \Omega_h$ . The discrete comparison principle implys that  $V \leq W$  on  $\Omega_h$ . 

4.9

Proof. To verify: 
$$L_h v = \lambda v$$
  

$$\frac{1}{h^2} 4v_{k,l} - v_{k,l+1} - v_{k,l-1} - v_{k+1,l} - v_{k-1,l} = \lambda_{\alpha,\beta}$$

$$\frac{1}{h^2} 4\sin(\alpha \pi kh) \sin(\beta \pi lh) - \sin(\alpha \pi (k+1)h) \sin(\beta \pi lh) \sin(\alpha \pi (k-1)h) \sin(\beta \pi lh)$$

$$-\sin(\alpha \pi kh) \sin(\beta \pi (l+1)h) - \sin(\alpha \pi kh) \sin(\beta \pi (l-1)h)$$

$$= \frac{1}{h^2} \sin(\alpha \pi kh) \sin(\beta \pi lh) 4(\sin^2(\frac{\alpha \pi h}{2}) + \sin^2(\frac{\beta \pi h}{2})$$
(3)

Hence,  $\lambda_{\alpha,\beta} = \frac{4}{h^2} (\sin^2(\frac{\alpha \pi h}{2}) + \sin^2(\frac{\beta \pi h}{2})).$ Compared with the eigenvalues of  $-\nabla (\alpha^2 + \beta^2)\pi^2$ , It's obvious that the small ones are better approximated for the property of sin around x = 0. 

Problem 2. To solve the boundary value problem

$$-u_{xx}(x) = f(x), \quad x \in (0,1).$$
(4)

with boundary condition  $u(0) = u(1) = 0, f \in C^0$ , we subdivide interval [0,1] into n equal subintervals with h = 1/n. Let  $x_j = jh$ , j = 0, ..., n, we are looking for  $u_j$ , the approximations to the exact solution  $u(x_i)$  at  $x_i$ .

(a) (Formulation) If we use central differences to approximate  $u_{xx}$ ,

$$u_{xx}(x_i) \simeq \frac{u_{i+1} - 2u_i + u_{i-1}}{h^2}.$$
 (5)

write down the resulting finite difference scheme (including boundary condition), and the associated linear system Au = F for the unknowns, specify A, u and F.

- (b) (Existence and Uniqueness) Prove that A is nonsingular, therefore the finite difference scheme has a unique solution. hint: there are many ways to do this, one way is to show that  $v^T A v > 0$  for any  $v \neq 0$ , namely, A is symmetrically positive definite.
- (c) (Numerics) A is a tri-diagonal matrix, Au = F can be efficiently solved by Gaussian elimination method which will be introduced later. In this homework, suppose that  $f = (3x + x^2)e^x$ , implement the numerical scheme. Take n = 4, plot the solution you obtain.
- (d) (Maximum Principle) For  $v \in \mathbb{R}^m$ , we say that  $v \ge 0$  if  $v_i \ge 0$  for  $1 \le i \le m$ . Show that if Aw = v and  $v \ge 0$ , then  $w \ge 0$ . Furthermore, this implies that  $\alpha_{ij} \ge 0$ , where  $\alpha_{ij}$  are the entries of  $A^{-1}$ . Use this property to show that if  $f \ge 0$ , then  $u_j \ge 0$ , for  $j = 0, \ldots, n$ .
- (e) (Discrete Stability) The function  $v(x) = \frac{x(1-x)}{2}$  satisfies

$$-\frac{v(x_{j+1}) - 2v(x_j) + v(x_{j-1})}{h^2} = 1.$$
(6)

Use this to show that the entries  $\alpha_{ij}$  of  $A^{-1}$  satisfies

$$0 \le \sum_{j=1}^{n-1} \alpha_{ij} \le \frac{1}{8}.$$
 (7)

Prove that

$$\max_{1 \le i \le n-1} |u_i| \le \frac{1}{8} \max_{1 \le i \le n-1} |f(x_i)|$$
(8)

(f) (Truncation Error) Like ODE, we can define truncation error,

$$T_j = -\frac{u(x_{j+1}) - 2u(x_j) + u(x_{j-1})}{h^2} - f(x_j)$$
(9)

Calculate the leading order term of  $T_i$ .

(g) (Error Equation) Let  $e_j = u(x_j) - u_j$  be the discretization error. Show that  $e_j$  satisfies the equation Ae = T, where  $e = (e_1, \ldots, e_{n-1})^T$  and  $T = (T_1, \ldots, T_{n-1})^T$ . Using (8) to prove the convergence result

$$\max_{1 \le i \le n-1} |u(x_i) - u_i| \le \frac{h^2}{96} \max_{0 \le x \le 1} |u^{(4)}(x)|.$$
(10)

(h) (Justification) When  $f = (3x + x^2)e^x$ , the exact solution is  $u(x) = x(1-x)e^x$ . Take n = 4, 8, 16, 32, 64, 128, 256, and compute numerical solutions  $u^n$ . Calculate  $||u - u^n||_{\infty} := \max_{1 \le i \le n-1} |u(x_i) - u_i^n|$ , plot (log-log) the convergence with resepct to n. Numerically estimate the prefactor in the estimate  $||u - u^n||_{\infty} \simeq Ch^{\alpha}$ , compare it with the result in (10)

Solution (a):

$$A = \begin{pmatrix} \frac{2}{h^2} & -\frac{1}{h^2} & & \\ -\frac{1}{h^2} & \frac{2}{h^2} & -\frac{1}{h^2} & \\ & \ddots & \ddots & \ddots & \\ & -\frac{1}{h^2} & \frac{2}{h^2} & -\frac{1}{h^2} \\ & & & -\frac{1}{h^2} & \frac{2}{h^2} \end{pmatrix}, \ u = \begin{pmatrix} u_1 \\ u_2 \\ \vdots \\ u_{n-1} \end{pmatrix}, \ F = \begin{pmatrix} f_1 \\ f_2 \\ \vdots \\ f_{n-1} \end{pmatrix}$$
(11)

Solution (b):

Matrix that satisfies 1 weakly diagonally dominant, 2 symmetric, 3 positive diagonal elements are positive definite.

Solution (d): Analogy with Discrete Maximum Principle. Solution (e):

*Proof.* v(x) attains its maximum  $\frac{1}{8}$  at  $x = \frac{1}{2}$ . Hence  $v(x_j) \leq \frac{1}{8}$  for j = 1, ..., n. Moreover,  $v = A^{-1}\mathbf{1}$ . (7) is proved then. And noticing that  $a_{i,j} \geq 0$ , it implies  $||A^{-1}||_{\infty} \leq \frac{1}{8}$ . (8) is proved then.

Solution (f): omitted

Solution (g): It can be proved based on truncation error (f) combined with discrete stability (e)  $\hfill \Box$