## Computational methods-Lecture 11

Eigenvalues; singular value decomposition; power method

## 1 Eigenvalues and eigenvectors

Recall:
For a square matrix $A$, if there exists $\lambda$ and $x \neq 0$ such that

$$
A x=\lambda x
$$

then $\lambda$ is called an eigenvalue and $x$ is called an eigenvector. The pairm $(\lambda, x)$ is called an eigen-pair.

The eigenvalues are roots of the characteristic polynomial

$$
\varphi(\lambda)=\operatorname{det}(\lambda I-A)
$$

Theorem 1 (Schur theorem). For a real square matrix $A$, there exists an orthogonal matrix $Q$ such that

$$
Q^{T} A Q=\left(\begin{array}{cccc}
R_{11} & R_{12} & \cdots & R_{1 m} \\
& R_{22} & \cdots & R_{2 m} \\
& & \cdots & \vdots \\
& & & R_{m m}
\end{array}\right)
$$

where $R_{i i}$ is a number or a $2 \times 2$ matrix with two complex eigenvalues, conjugate with each other.

If $A$ is real symmetric, all $R_{i i}$ are numbers and the matrix on the right hand side is in fact diagonal.

The largest eigenvalues or smallest eigenvalues can often be reduced to the max or min of the Rayleigh quotient:

$$
R(x):=\frac{\langle A x, x\rangle}{|x|^{2}} .
$$

## 2 Singular value decomposition (SVD)

For non-square matrix, there is no eigenvalues. However, we can generalize the idea to the so-called singular values. In particular, consider $A$ of size $m \times n$ and $A^{T} A$.

Since $A^{T} A$ is positive semi-definite, we can find orthogonal matrix $V$ of size $n \times n$ such that

$$
A^{T} A=V D V^{T}
$$

Here, the columns of $V$ are eigenvectors of $A^{T} A$ and

$$
V^{T}\left(A^{T} A\right) V=D=\left(\begin{array}{cccc}
\sigma_{1}^{2} & & & \\
& \sigma_{2}^{2} & & \\
& & \cdots & \\
& & & \sigma_{n}^{2}
\end{array}\right)
$$

with $\sigma_{1} \geq \sigma_{2} \geq \cdots \geq \sigma_{n} \geq 0$.
Define the matrix $\Sigma$ of size $m \times n$. Let $\Sigma_{i i}=\sigma_{i}$ for $i \leq \min (m, n)$, and other entries are zero.

Suppose $\sigma_{k}>0$ and $\sigma_{k+1}=0$ (if all nonzero, then $k=n$; if all zero, then $k=0$ ). Consider

$$
u_{i}=\frac{1}{\sigma_{i}} A v_{i}, \quad i=1, \cdots, k
$$

where $v_{i}$ 's are the columns of $V$.
We have the following observation:
Lemma 1. $k \leq \min (m, n)$ and $u_{i}$ 's are ortho-normal.
The first is clear. The reason is that $k$ equals the rank of $A^{T} A$ and thus the rank of $A$. To show that they are orthonormal, we just note

$$
u_{i}^{T} u_{j}=\frac{1}{\sigma_{i}^{2}} v_{i}^{T} A^{T} A v_{j}
$$

and use the fact that $v_{i}$ 's are eigenvectors.
Then, we can add $m-k$ orthonormal vectors into the list $\left\{u_{1}, \cdots, u_{k}\right\}$ to form an orthonormal basis of $\mathbb{R}^{m}$. Let $U$ be the matrix whose columns are these vectors. Then, one has:

Theorem 2 (The singular value decomposition). $A=U \Sigma V^{T}$.
Proof. One only has to verify

$$
A V=U \Sigma
$$

For $i \leq k, A v_{i}=\sigma_{i} u_{i}$ holds by definition. For $i>k, A^{T} A v_{i}=0$, so $v_{i}^{T} A^{T} A v_{i}=0$. Hence, $A v_{i}=0$. Clearly, $\sigma_{i} u_{i}=0$ since $\sigma_{i}=0$.

The SVD tells us that

$$
A=\sum_{i=1}^{k} \sigma_{i} u_{i} v_{i}^{T}
$$

Exercise: Show that $u_{i}$ 's are eigenvectors of $A A^{T}$.
Exercise: Show that the 2-norm of $A$ is the largest singular value and the Frobenius norm is the square root of the sum of squares of all singular values.

Example find the singular value decomposition for

$$
A=\left(\begin{array}{cc}
1 & 0 \\
2 & 0 \\
0 & -1 \\
0 & 2
\end{array}\right)
$$

## 3 Power method

The idea of power method is as follows: suppose $\lambda_{1}$ is the eigenvalue with largest magnitude and the multiplicity is 1 :

$$
\left|\lambda_{1}\right|>\left|\lambda_{2}\right| \geq \cdots\left|\lambda_{n}\right|>0
$$

Suppose first that $A$ has $n$ independent eigenvectors. Then, for any $x_{0}$

$$
x_{0}=\sum_{j=1}^{n} \beta_{j} v_{j} .
$$

If we multiply $A$, we have

$$
A x_{0}=\sum_{j=1}^{n} \beta_{j} \lambda_{j} v_{j} .
$$

If we do this $k$ times

$$
A^{k} x_{0}=\sum_{j=1}^{n} \beta_{j} \lambda_{j}^{k} v_{j} .
$$

The observation is that $\left|\lambda_{1}^{k}\right| \gg\left|\lambda_{j}\right|^{k}$ for $j \geq 2$. Hence, the vector

$$
A^{k} x_{0}
$$

will be close to the leading eigenvector. This then motivates the power method for finding the leading eigen-pair.

If $\left|\lambda_{1}\right|<1$, the iteration $x^{(k)}=A^{k} x_{0} \rightarrow 0$. If $\left|\lambda_{1}\right|>1$, it diverges. Hence, to get a regular result, we need to normalize the vectors.

1. Choose $x_{0} \neq 0 ; x \leftarrow x_{0}$
2. For $k=1, \cdots$
$u \leftarrow A x$
$x=u / u_{i_{0}}$, where $i_{0}$ is chosen such that $\left|u_{i_{0}}\right|=\|u\|_{\infty}$.
3. Lastly, compute the eigenvalue

$$
\lambda \leftarrow \frac{x^{T} A x}{x^{T} x}
$$

There are some observations:

- If the matrix $A$ is sparse, then the matrix-vector multiplication can be fast.
- If there no enough eigenvectors, the method still works. (Try to show this using Jordan block).
- If $\lambda_{1}$ has multiplicity larger than 1 , the method still works.

Clearly, if we set $\mu_{k}=u_{i_{0}}$ in the $k$ th iteration, then

$$
x^{(m)}=\frac{A^{m} x_{0}}{\prod_{k \leq m} \mu_{k}}
$$

Using this, it is easy to see
Theorem 3. If in the expansion of $x_{0} \beta_{1} \neq 0$, then $x^{(m)}$ converges to the leading eigenvector and $\lambda^{(k)}$ converges to the eigenvalue. Moreover, the error estimate holds

$$
\left|\lambda^{(k)}-\lambda_{1}\right| \leq C\left|\frac{\lambda_{2}}{\lambda_{1}}\right|^{k} .
$$

If the matrix $A$ is real symmetric, the error can be improved to $\left|\lambda_{2} / \lambda_{1}\right|^{2 k}$
If one desires other eigenvalues, one can do shifting or do deflation (like the classical Wielandt deflation). We omit these here.

## 4 The Householder's method

Let $w \in \mathbb{R}^{n}$ with $|w|=1$. We call the following matrix

$$
P=I-2 w w^{T}
$$

the Householder transform.
The Householder matrix is orthogonal. Its eigenvalues are 1 and -1 .

$$
P^{-1}=P^{T}=P .
$$

The Householder transform is in fact the reflection about the hyperplane perpendicular to $w$. To see this, we decompose $v$ into $v=x+y$ where $x \| w$ while $y \perp w$. Then,

$$
P v=P(x+y)=x-y .
$$

Due to this geometric meaning, for any $x, y$ with $|x|=|y|$, we can find such a reflection operator that maps $x$ into $y$. In fact, the difference between $x$ and $y$ is perpendicular to the symmetric plane, so parallel to $x-y$. Hence, we can choose

$$
w=\frac{x-y}{\|x-y\|_{2}} .
$$

In other words,

$$
P_{x \rightarrow y}=I-2 \frac{(x-y)(x-y)^{T}}{\|x-y\|_{2}^{2}}\left(=I-2 \frac{(x-y) \otimes(x-y)}{|x-y|^{2}}\right) .
$$

With this observation, we can get a useful result:
Proposition 1. For any nonzero $x$, there exists a Householder transform $H$ such that

$$
H x=-\sigma e_{1},
$$

where

$$
\sigma=\operatorname{sgn}\left(x_{1}\right)\|x\|_{2}
$$

According to the construction above,

$$
H=I-\beta^{-1} u u^{T}, \quad u=x+\sigma e_{1}, \quad \beta=\frac{1}{2}\|u\|^{2}=\sigma\left(\sigma+x_{1}\right) .
$$

